

APPROXIMATION ALGORITHMS

GREEDY ALGORITHMS & LOCAL SEARCH

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# TODAY

## FOUR CASE STUDIES:

- SCHEDULING OVERLAP JOBS ← GREEDY
  - K-CENTER PROBLEM ← LOCAL SEARCH
  - SCHEDULING JOBS IN PARALLEL ← LOCAL SEARCH
  - METRIC TRAVELLING SALES PERSON ← LOCAL SEARCH
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- ```
graph TD; LS[LOCAL SEARCH] --> S1[SCHEDULING OVERLAP JOBS]; LS --> S2[K-CENTER PROBLEM]; LS --> S3[SCHEDULING JOBS IN PARALLEL]; LS --> S4[METRIC TRAVELLING SALES PERSON]; G[GREEDY] --> S1;
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# SCHEDULING OVERLAP JOBS

INPUT: FOR  $i = 1, \dots, n$ :

$p_i \geq 0$ : TIME NEEDED TO COMPLETE JOB  $i$

$r_i \geq 0$ : THE EARLIEST TIME JOB  $i$  CAN START

$d_i \leq 0$ : AMOUNT OF TIME LEFT FOR JOB  $i$

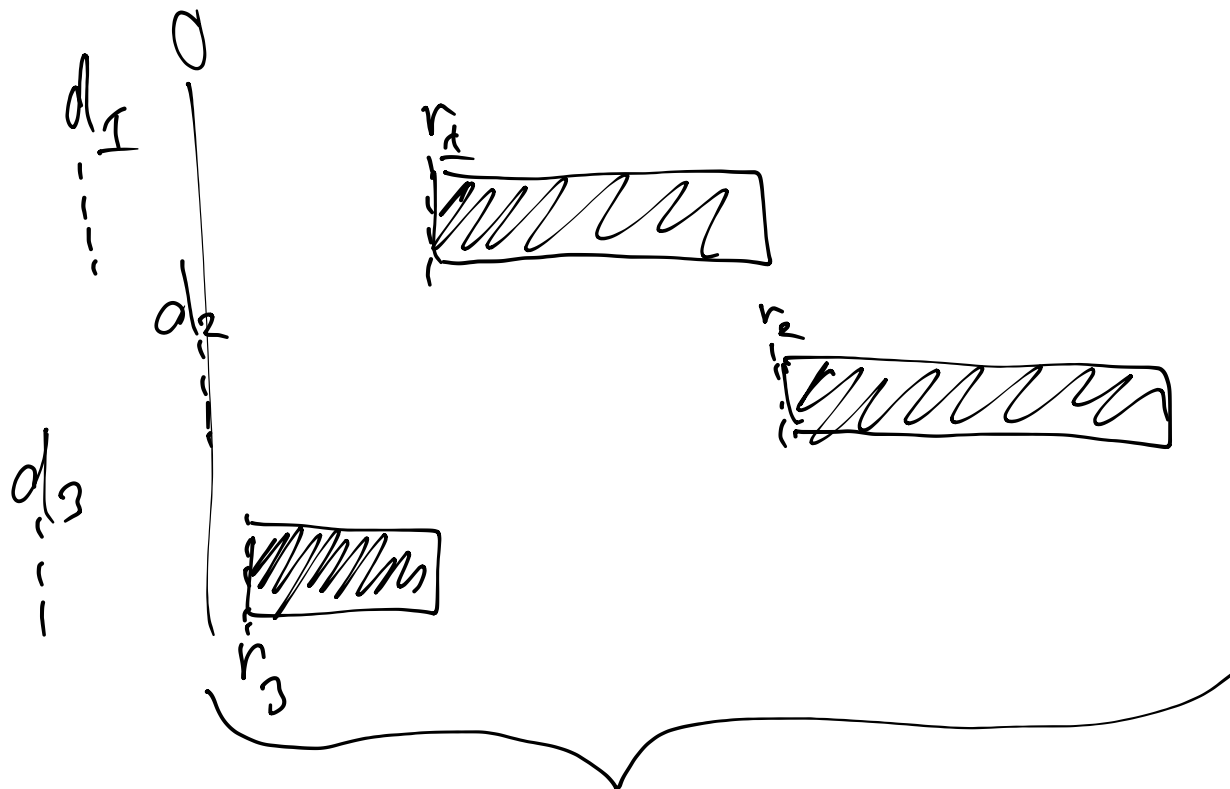
OBJECTIVE: CREATE SCHEDULE WITH NO OVERLAPS  
THAT MINIMIZES THE MAXIMUM LATENCY

$$\max_i c_i - d_i$$

WHERE  $c_i$  IS THE COMPLETION  
TIME OF JOB  $i$ .

# GREEDY HEURISTIC

AT TIME  $t$ , CONSIDER UNSCHEDULED JOBS WITH  $r_i \geq t$  AND SCHEDULE THE ONE WITH THE EARLIEST DUE TIME  $d_i$ .



PAUSE TO THINK:  
FIND AN INPUT W.  
 $n=2$  JOBS WHERE  
GREEDY'S SCHEDULE  
HAS COST  $\geq 1.99 \text{OPT}$

↑  
OPTIMAL  
COST

$$\text{COST: } r_3 + p_3 + p_1 + p_2 - d_2$$

# ANALYSIS OF GREEDY

LAST JOB SCHEDULED STOPS AT TIME  $C_j$ .

COST OF GREEDY

$$= C_j - d_j$$

$$= \min_{j \in S} (r_j) + \sum_{j \in S} p_j - d_j \leq 2 \text{OPT}$$

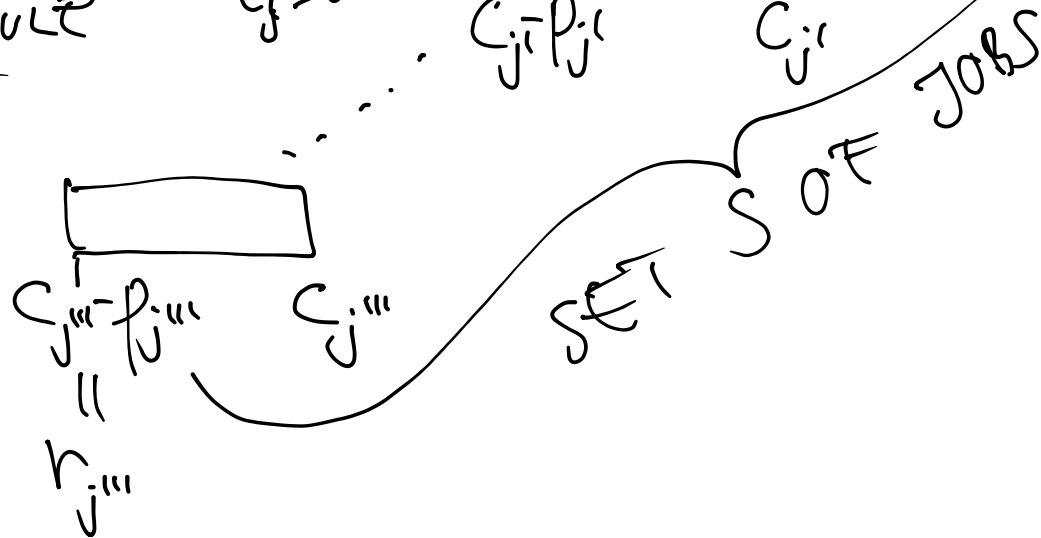
$\leq$  COMPLETION  
TIME FOR ANY  
SCHEDULE

$$\leq \text{OPT}$$

$\leq \text{OPT}$   
SINCE  
 $C_j \geq 0$

TIGHT ANALYSIS

$$C_j - p_j \quad C_j = \min_{j \in S} (r_j) + \sum_{j \in S} p_j$$

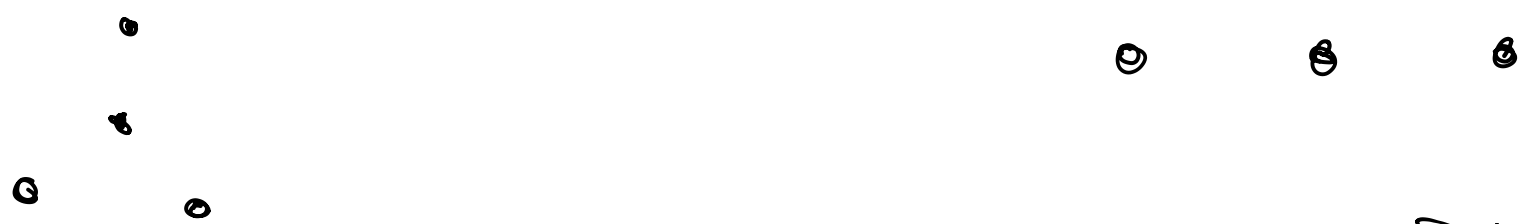


# k-center problem

GIVEN POINT SET  $P$ , COVER  
IT WITH  $k$  DISKS OF RADIUS  $r$   
WHERE  $r$  IS AS SMALL AS POSSIBLE.

OBJECTIVE: CHOOSE  $S \subseteq P$  SUCH THAT  $|S|=k$  AND  $\max_{x \in P} d(x, S)$  IS MINIMIZED

distance to point set:  
$$d(x, S) = \min_{y \in S} d(x, y)$$

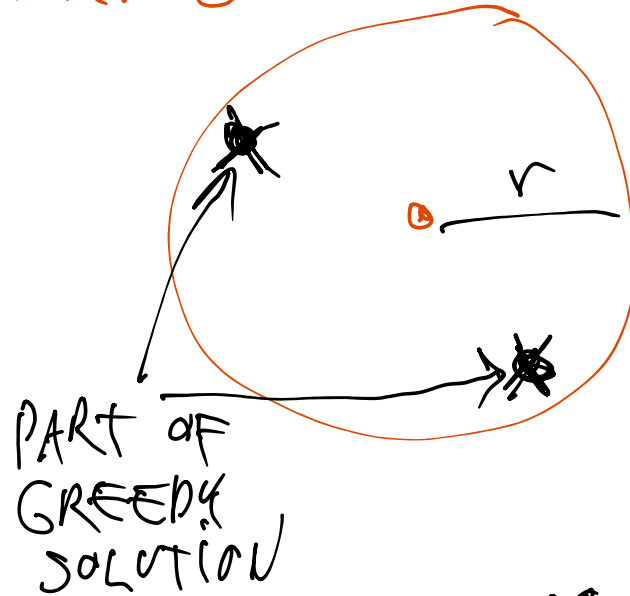
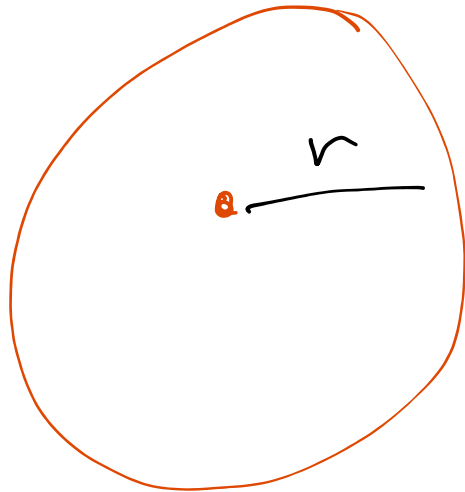


PAUSE AND THINK:  
GREEDY CAN RETURN  
A  $k$ -CENTER THAT IS  
OF RADIUS  $2 \cdot \text{OPT}$ .

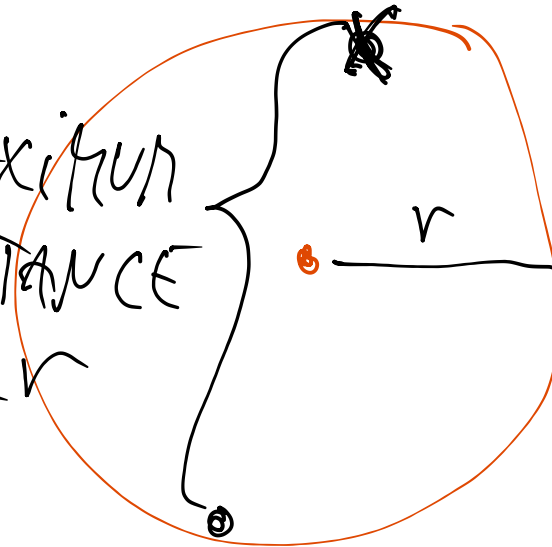
GREEDY: - START WITH  $S = \emptyset$ .  
- ADD POINT  $x \in P$  TO  $S$  THAT  
MAXIMIZES  $d(x, S)$   
- REPEAT UNTIL  $|S|=k$

# ANALYSIS OF GREEDY

CONSIDER AN **OPTIMAL** SOLUTION



MAXIMUM  
DISTANCE  
 $\leq 2r$



CASE 1:

GREEDY SELECTS  
A POINT FROM  
EACH CLUSTER ✓

CASE 2:

GREEDY OMITTS THE  
POINTS OF SOME  
CLUSTER.

⇒ PICKS TWO POINTS  
IN SOME CLUSTER  
⇒ ALL DISTANCES TO  
S ARE  $\leq 2r$ . ✓

# SCHEDULING JOBS IN PARALLEL

INPUT: INTEGER  $m$ : NUMBER OF MACHINES

$p_1, \dots, p_n \geq 0$ : PROCESSING TIMES

OBJECTIVE: ALLOCATE JOBS TO MACHINES  
TO MINIMIZE  $\max_i C_i$


## LOCAL SEARCH:


- START WITH ANY FEASIBLE SOLUTION

- REPEAT:

MAKE LOCAL CHANGE: MOVE ONE JOB  
TO IMPROVE MAKESPAN  
UNTIL NO LONGER POSSIBLE

M1 

M2 

M3 

PAUSE TO THINK:  
SHOW THAT LOCAL  
SEARCH MAY NOT  
FIND THE OPTIMAL  
SOLUTION.  
HOW LARGE A GAP  
CAN YOU GET?

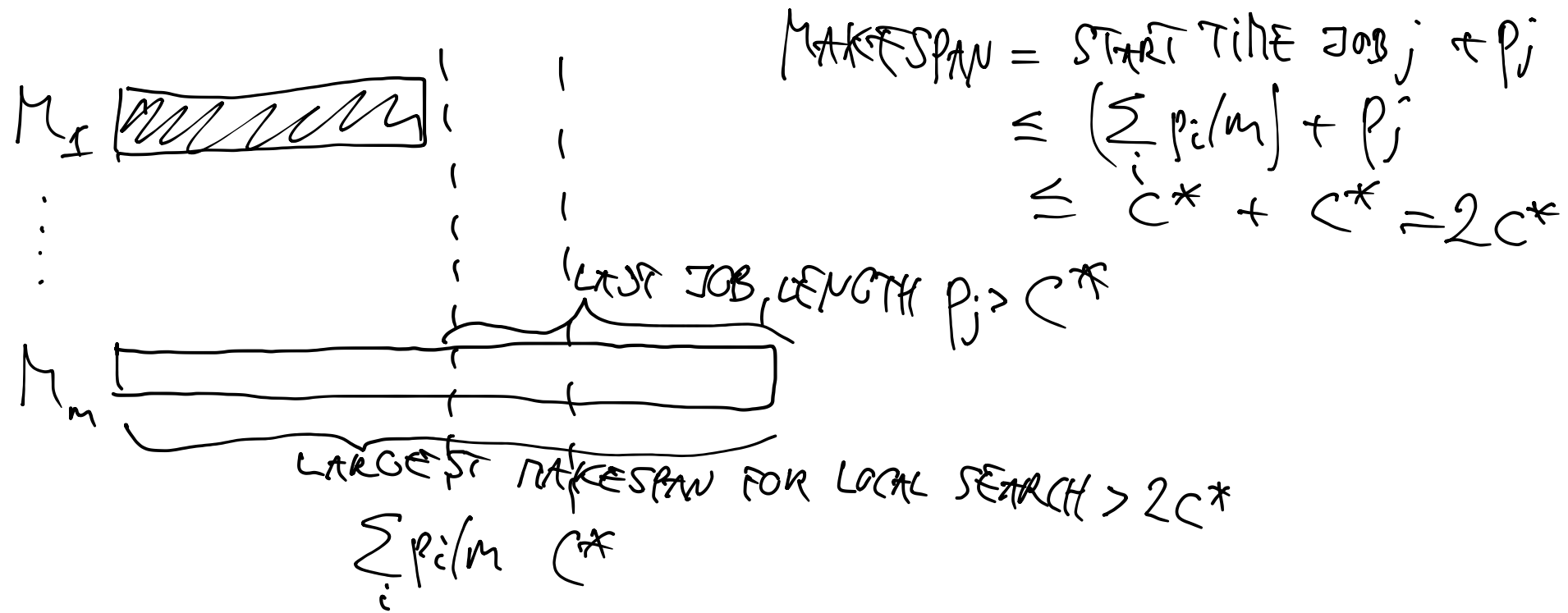


# ANALYSIS OF LOCAL SEARCH

LET  $C^*$  BE THE COST OF AN OPTIMAL SCHEDULE

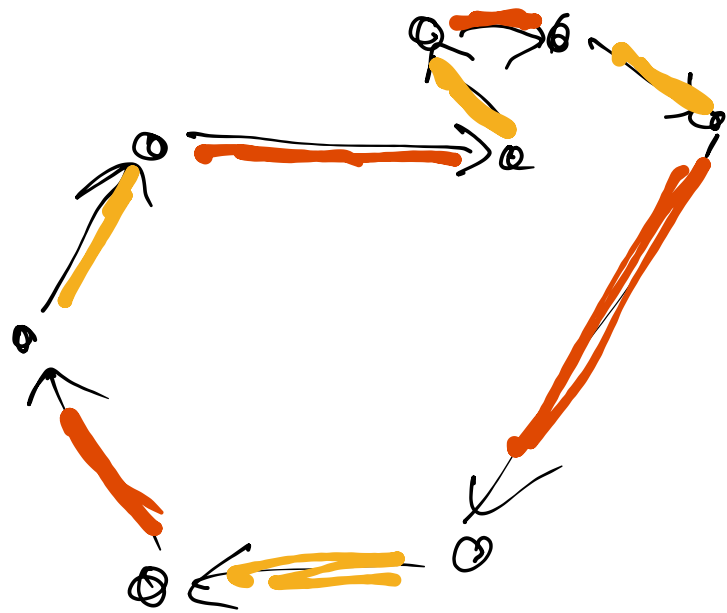
LEMMA:  $C^* \geq \sum_i p_i / m$  (WORST COST CANNOT BE SMALLER THAN AVG.)

SUPPOSE LOCAL SEARCH RETURNS SOLUTION OF COST  $> 2C^*$ .



# METRIC TRAVELING SALESPERSON PROBLEM

GIVEN POINT SET  $P$  AND A METRIC OF DISTANCES,  
 $C_{ij} = d(x_i, x_j)$  FOR  $x_i, x_j \in P$ , FIND SHORTEST TOUR  $T$   
OF ALL POINTS. MINIMIZE  $\sum_{(x_i, x_j) \in T} C_{ij}$ .



OBSERVATION:

- a) A TOUR INCLUDES A SPANNING TREE
- b) IF  $|P|$  IS EVEN, A TOUR CONSISTS OF TWO MATCHINGS

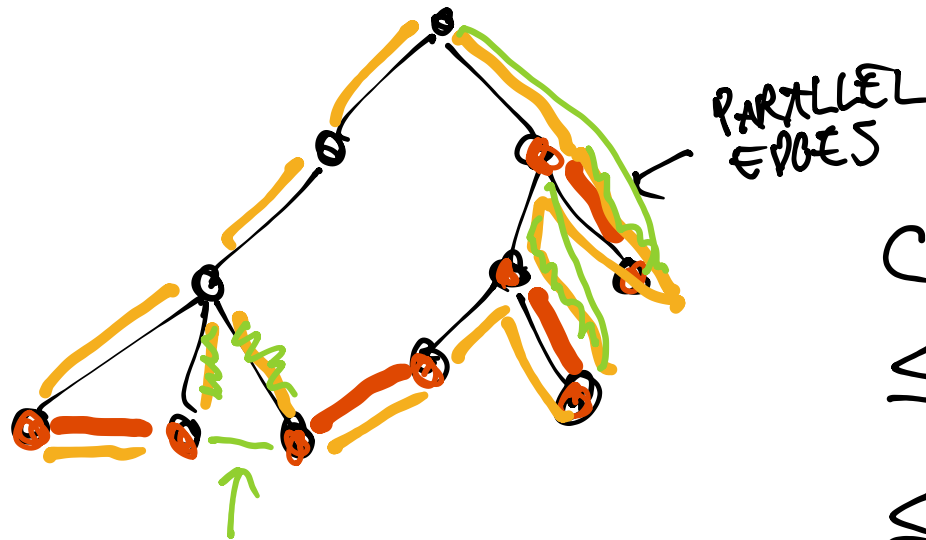
OPT  $\geq$  2x MIN WEIGHT  
MATCHING

OPT  $\geq$  MIN WEIGHT  
SPANNING TREE

← APP? →

# CHRISTOFIDES ALGORITHM (1976)

- 1) COMPUTE MINIMUM SPANNING TREE  $T$
- 2) ON THE ODD-DEGREE NODES IN  $T$ , COMPUTE A MINIMUM WEIGHT MATCHING  $M$
- 3) CONSTRUCT TOUR FROM EDGES OF  $T$  AND  $M$  WITH SHORTCUTS



COST OF TOUR

$\leq$  WEIGHT OF  $T$  + WEIGHT OF  $M$

$\leq$  OPT +  $\frac{1}{2}$  OPT

KARLIN, KLEIN & CHARAN (2020):  
APPROX FACTOR  $\frac{3}{2} - \epsilon$  FOR  $\epsilon > 10^{-36}$